

# Intro to Numerical Methods

## Class I: The Neoclassical Investment Model and VFI

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# The Neoclassical Investment Model

## Core model structure

Firms invest to maximize the present value of profits, equating the marginal benefit and cost of capital. Households own firms, supply labor, and consume dividends.

## Key mechanism

Investment raises future productive capacity at the cost of foregone consumption.

## Applications:

- Studying business investment cycles.
- Studying effects of monetary and fiscal policy.
- Understanding firm dynamics and growth.
- DSGE NK models, heterogeneous agents and firms.

# The Firm's Problem

- Firm owns physical capital  $K_t$  and chooses investment  $I_t$ .
- Production function:

$$Y_t = F(K_t, N_t)$$

- Capital accumulation:

$$K_{t+1} = (1 - \delta)K_t + I_t$$

- Profits:

$$D_t = F(K_t, N_t) - w_t N_t - I_t$$

- Problem:

$$\max_{\{I_t, N_t\}} \sum_{t=0}^{\infty} \beta^t D_t$$

# First-Order Conditions

- **Labor demand:**

$$w_t = F_N(K_t, N_t)$$

- ▶ Wages equal the marginal product of labor.

- **Capital Euler equation:**

$$1 = \beta \left[ F_K(K_{t+1}, N_{t+1}) + (1 - \delta) \right]$$

- ▶ The marginal cost of investing today equals the discounted marginal return to capital tomorrow.

# Household Problem

## Preferences (risk-neutral)

$$\max_{\{C_t, S_{t+1}, B_{t+1}\}_{t \geq 0}} \sum_{t=0}^{\infty} \beta^t C_t$$

## Budget constraint

$$C_t + p_t S_{t+1} + q_t B_{t+1} = w_t \bar{N} + (p_t + D_t) S_t + B_t$$

$p_t$ : price of one share;  $D_t$ : dividend per share.  $S_t$ : shares;  $B_t$ : risk-free bond holdings.  $\bar{N}$ : inelastic labor supply (normalize to 1 if desired).

## FOCs / Pricing:

$$p_t = \underbrace{\beta [D_{t+1} + p_{t+1}]}_{\text{NPV of dividends}}, \quad \underbrace{q_t}_{\text{Risk-free bond price}} = \beta$$

# Closing the Model

Market clearing conditions:

- Goods market clears:  $Y_t = F(K_t, N_t)$ .
- Labor market clears:  $N_t = \bar{N}$ .
- Capital market clears:  $S_t = 1$ .
- Bonds are in zero net supply:  $B_t = 0$ .

## Resource constraint

Combine the market clearing conditions with the household budget constraint and the firm dividend to get:  $C_t + I_t = Y_t = F(K_t, N_t)$ .

## From Competitive Equilibrium to Planner

Under perfect competition, constant returns, and no distortions, the competitive equilibrium allocation solves the planner's problem:

$$\max_{\{C_t, K_{t+1}\}} \sum_{t=0}^{\infty} \beta^t C_t$$

subject to the single feasibility constraint (resource constraint)

$$C_t + K_{t+1} = ZK_t^\alpha + (1 - \delta)K_t, \quad K_0 \text{ given.}$$

This is equivalent to imposing market clearing on the household problem and substituting firm FOCs into prices.

# From Sequential to Recursive Formulation

## Sequential Planner Problem:

$$\max_{\{C_t, K_{t+1}\}} \sum_{t=0}^{\infty} \beta^t C_t \quad \text{s.t.} \quad C_t + K_{t+1} - (1 - \delta)K_t = ZK_t^{\alpha}$$

## Step to Recursion:

- Take current capital  $K \equiv K_t$  as the *state*.
- Choose next period's capital  $K' \equiv K_{t+1}$  as the *control*.
- Use feasibility to solve for consumption:

$$C(K, K') = ZK^{\alpha} - (K' - (1 - \delta)K).$$

- Rewrite the lifetime problem recursively:

$$V(K) = \max_{K' \geq 0} \left\{ C(K, K') + \beta V(K') \right\}.$$

# Homework 1: Solve the following problem numerically...

## Planner problem

$$V(K) = \max_{K' \geq 0} \{ C(K, K') + \beta V(K') \},$$

...subject to...

$$C(K, K') = ZK^\alpha - (K' - (1 - \delta)K).$$

Discount factor:  $\beta = 0.96$ . Capital share in production:  $\alpha = \frac{1}{3}$ .

Depreciation rate:  $\delta = 0.10$ . Productivity level:  $Z = 1$ .

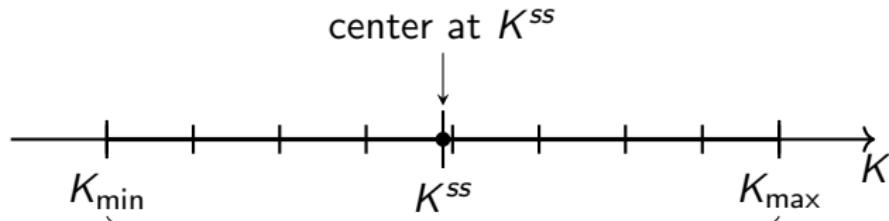
## First Step: Grid Centered at the Steady State

Compute the steady state:

$$1 = \beta(F_K(K^{ss}) + 1 - \delta) \Rightarrow K^{ss} = \left( \frac{\frac{1}{\beta} - (1 - \delta)}{\alpha Z} \right)^{\frac{1}{\alpha-1}}.$$

Center the grid around  $K^{ss}$ :

$$K_{\min} = (1 - \eta) K^{ss}, \quad K_{\max} = (1 + \eta) K^{ss}, \quad K_i \in \{K_{\min}, \dots, K_{\max}\}.$$



For this assignment I used  $\eta = 0.99$  (very wide range)

# VFI I: Maximization via Grid Search

## Algorithm:

- ① Initialize  $V^{(0)}(K_i) = 0$  for all  $i$ .
- ② For each  $K_i$ , evaluate

$$\text{RHS}(K_i, K_j) = C(K_i, K_j) + \beta V^{(n)}(K_j), \quad \forall K_j \in \{K_{\min}, \dots, K_{\max}\},$$

and set  $V^{(n+1)}(K_i) = \max_j \text{RHS}(K_i, K_j)$  with argmax policy  $K'(K_i)$ .

- ③ Stop when  $\|V^{(n+1)} - V^{(n)}\| < \varepsilon$ .

- *Pros:* simple, global maximizer.
- *Cons:* discrete  $K'$  (blocky policy)  $\rightarrow$  could be imprecise.

## VFI II: Interpolation + Golden Section Search

### Idea

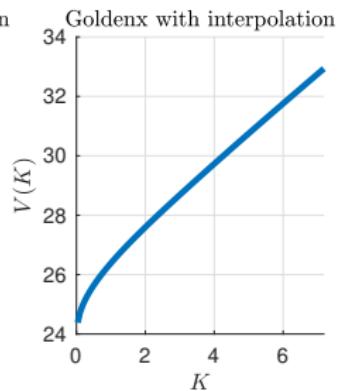
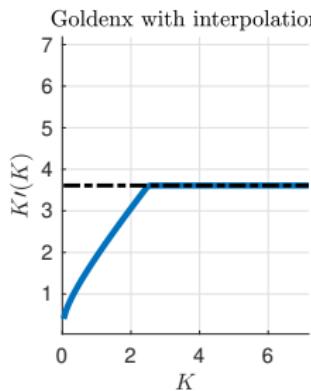
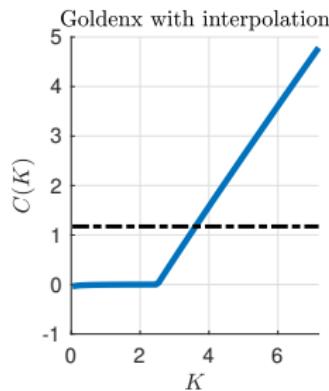
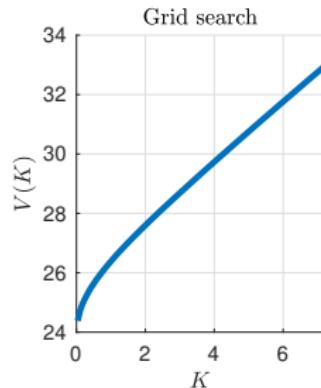
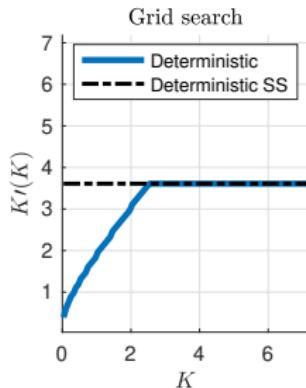
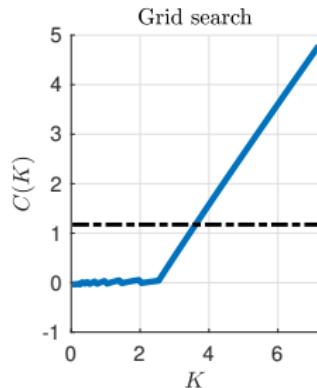
Keep the state grid for  $K$ , but treat the choice  $K'$  as *continuous* in  $[K_{\min}, K_{\max}]$ . Interpolate  $V(K')$  between nodes and use a 1D optimizer.

### Algorithm:

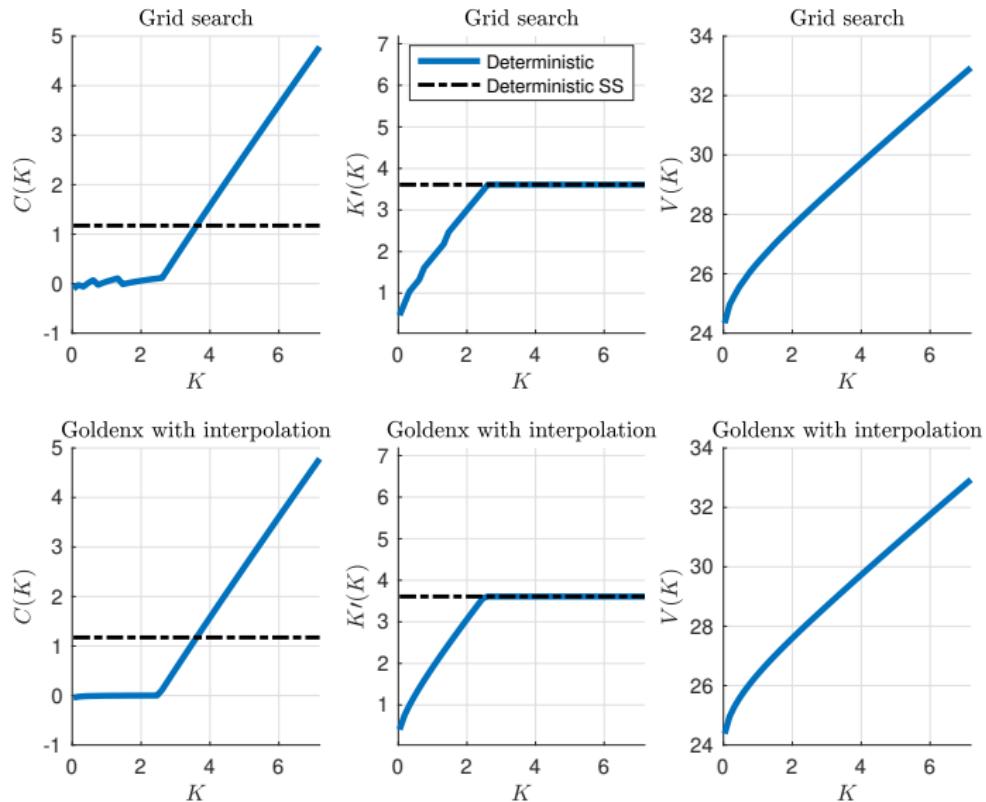
- ① Fix  $K_i$ , define  $g(K') = C(K_i, K') + \beta \tilde{V}^{(n)}(K')$ , where  $\tilde{V}$  is obtained via `interp1` (in Matlab).
- ② Maximize  $g(K')$  over  $[K_{\min}, K_{\max}]$  using golden section search (`goldenx`) (in Matlab).
- ③ Update  $V^{(n+1)}(K_i)$  and policy  $K'(K_i)$ . Iterate to convergence.

- *Pros:* smoother policies, higher accuracy, fewer evaluations.
- *Cons:* risk of local maxima.

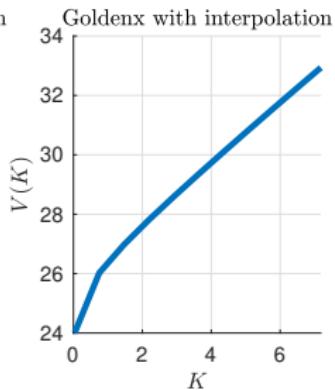
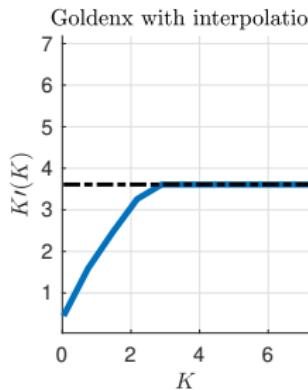
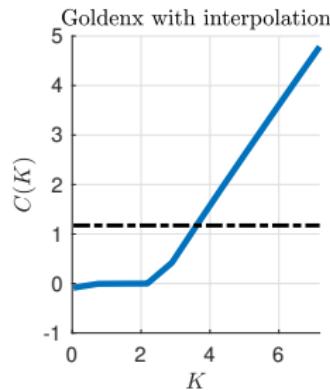
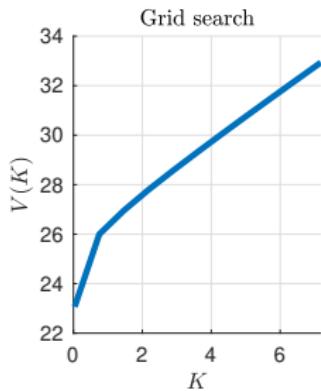
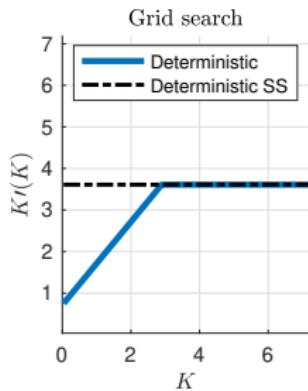
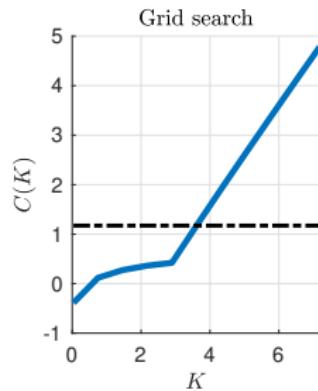
# Preview of Results with 101 Nodes in the Capital Grid



# Preview of Results with 51 Nodes in the Capital Grid



# Preview of Results with 11 Nodes in the Capital Grid



# Economic and Computational Takeaways

## Result

- In a frictionless, risk-neutral world, firms face no reason to smooth investment and the economy leaps directly to its steady state.

But we are in general equilibrium...

- Consumption is nonnegative and investment is resource-limited.

## Computational message

- Goldenx+interpolation performs well even with few nodes.

# GOOD LUCK!

# Golden Section Search

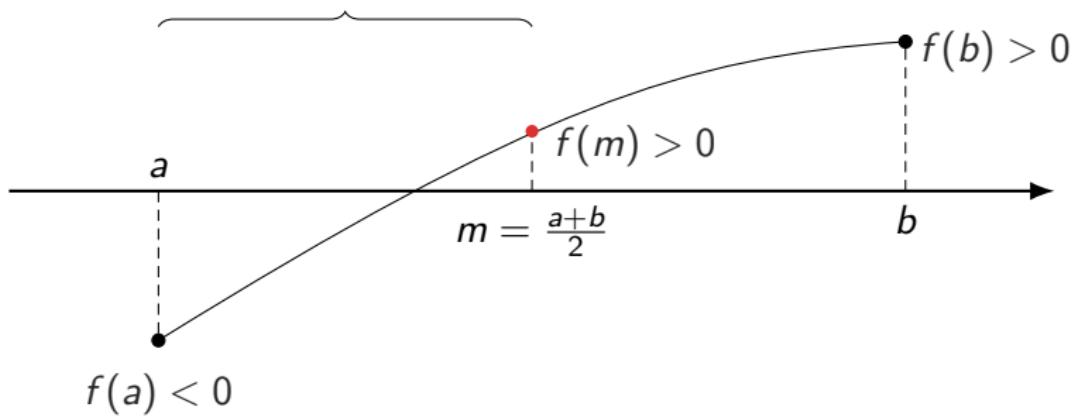
## What is it?

A method to find the maximum (or minimum) of a function in a **1D interval** without derivatives. It works by repeatedly narrowing down the interval where the optimum lies.

- For intuition, let's look at a simpler root-finding algorithm: the **bisection method**.

## Dichotomic (Bisection) method — Step 1

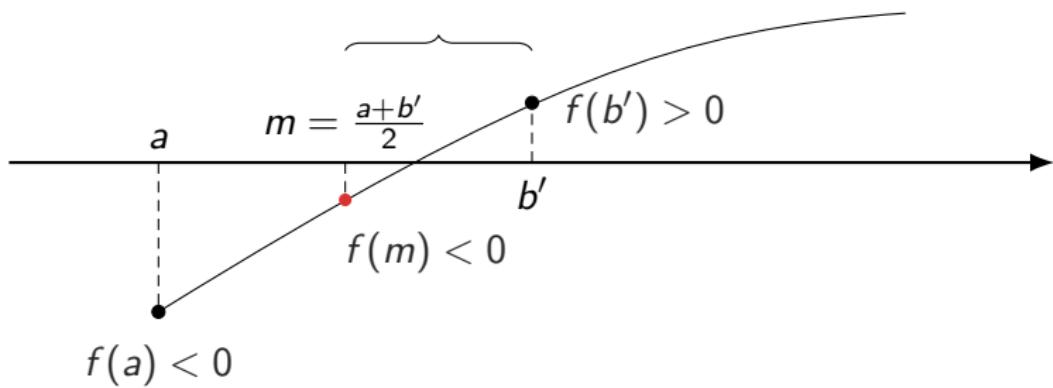
Since  $f(m) > 0$ , interval  $[a, m]$   
must contain sign change



## Dichotomic (Bisection) method — Step 2

- Now, reset endpoints: let  $m = b'$  and repeat with new  $m$ .

Since  $f(m) < 0$ , interval  $[m, b']$   
must contain sign change



# Golden Section Search

## Key idea

Split the interval using the “golden ratio”

$$\varphi = \frac{\sqrt{5}-1}{2} \approx 0.618,$$

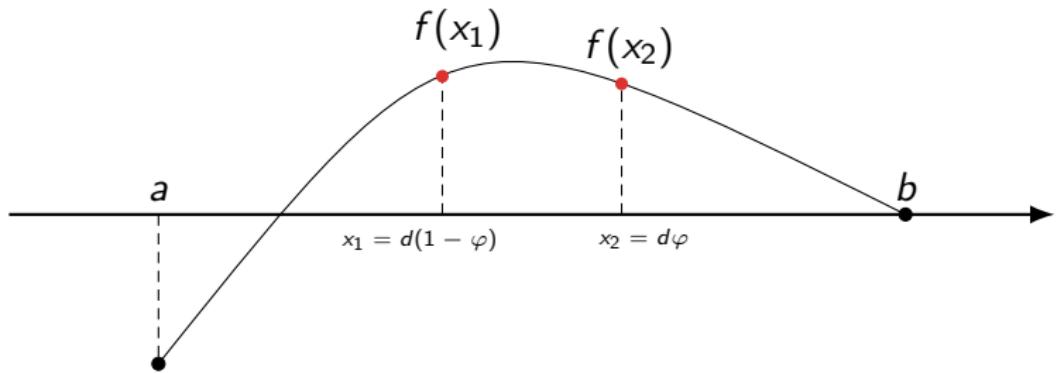
so that the function is only evaluated once per step.

## Intuition

Think of “zooming in” on the peak: each iteration cuts the search interval smaller and smaller, always keeping the point with the higher value.

## Golden Section Search — Step 1

- **Assumption:**  $f$  is unimodal on the search interval  $[a, b]$ .
- Define:  $d \equiv b - a$ .
- Pick  $x_1$  and  $x_2$  using the “golden ratio”  $\varphi$ .
- $f(x_1) > f(x_2) \implies$  maximum is to the left of  $x_2$ .



## Golden Section Search — Step 2

- Redefine:  $a = a', x_2 = b', x_1 = x_2', d' \equiv b' - a'$ .
- Repeat process, setting new  $x_1 = d'(1 - \varphi)$ .
- $f(x_1) < f(x_2) \implies$  maximum is to the right of  $x_1$ .

